

Scalable Kernelization for Maximum Independent Sets

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Maximum Independent Sets

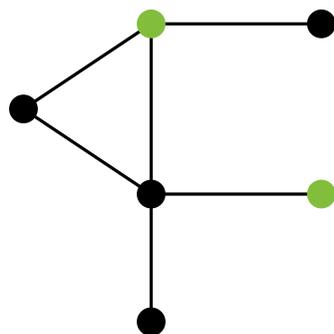
Independent Set (IS)

Given a graph $G = (V, E)$,

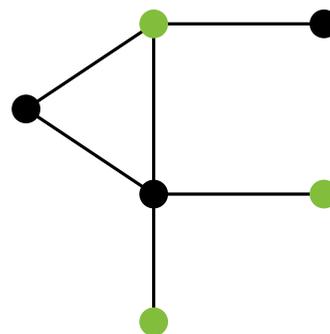
find $I \subseteq V$ such that $\forall u, v \in I : \{u, v\} \notin E$

- Find **Maximum** IS (MIS) I : for all IS I' of G : $|I| \geq |I'|$

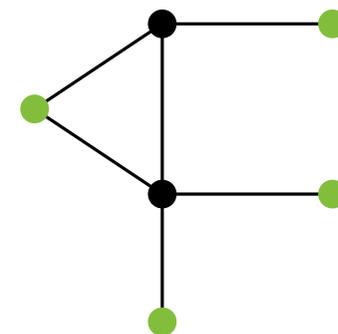
Independent set



maximal IS



maximum IS



Maximum Independent Sets

Independent Set (IS)

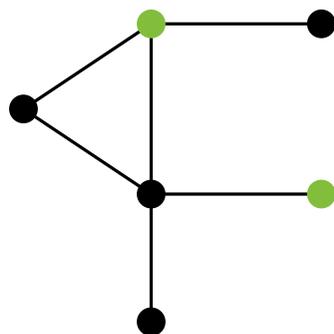
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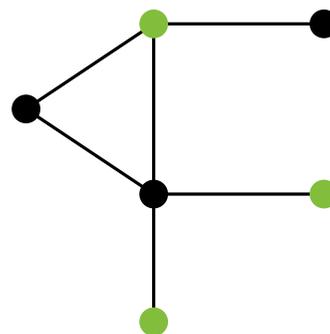
NP hard

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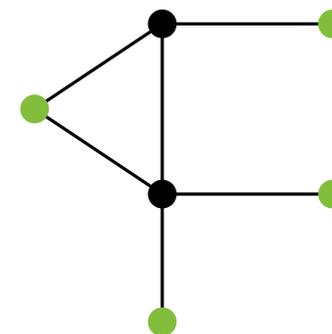
Independent set



maximal IS



maximum IS



Reduction Algorithm R :

- Input: G
- Output G' with $|G'| \leq |G|$

function KERNELMIS(G)

$G' \leftarrow R(G)$

$I' \leftarrow \text{MIS}(G')$

$I \leftarrow R^{-1}(G', I')$

return I

Reduction Algorithm R :

- Input: G  Kernel
- Output G' with $|G'| \leq |G|$

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Kernelization

Reduction Algorithm R :

- Input: G  Kernel
- Output G' with $|G'| \leq |G|$

Fast

polynomial

function KERNELMIS(G)

$G' \leftarrow R(G)$

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Slow $I \leftarrow R^{-1}(G', I')$

if exact

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Kernelization

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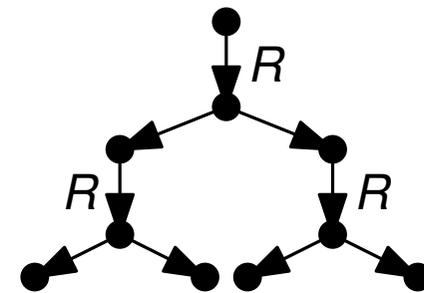
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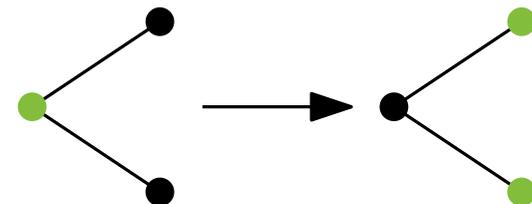
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Branch and Reduce



Local Search



Kernelization

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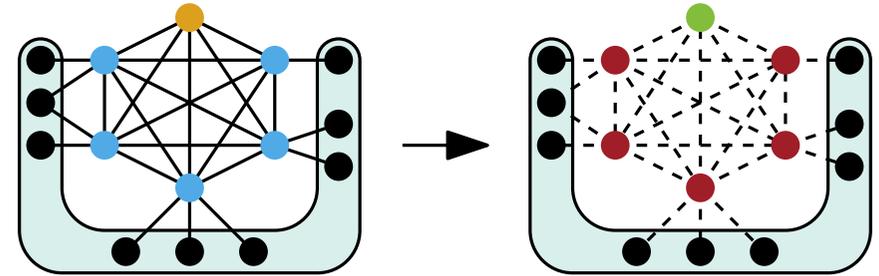
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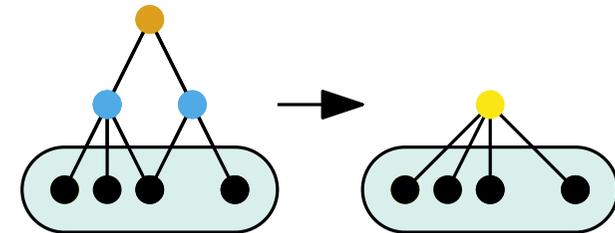
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Isolated Clique Reduction



Degree 2 Vertex Folding



- Twin Reduction
- Unconfined and Diamond Reduction
- LP via Maximum Bipartite Matching

Kernelization

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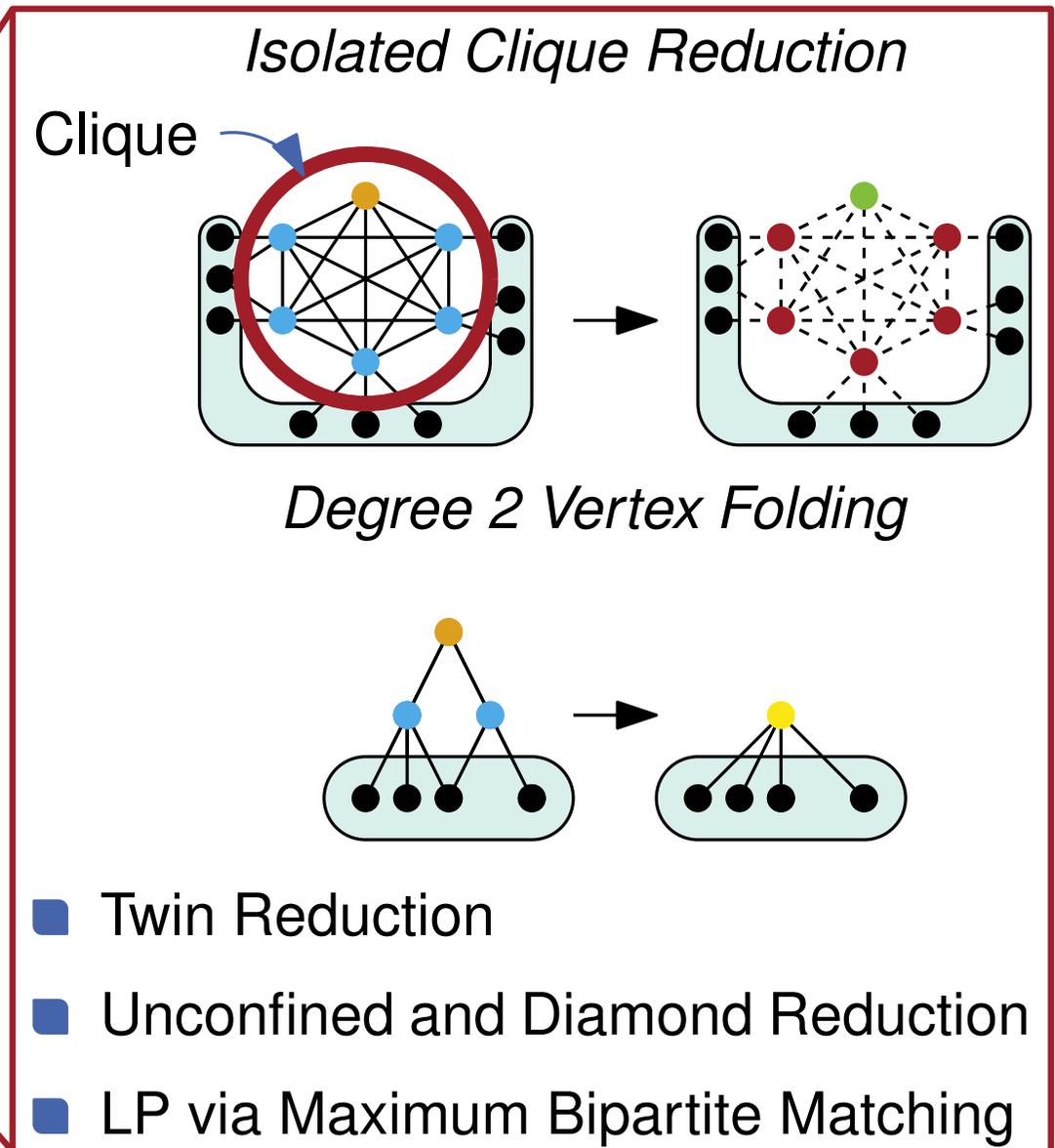
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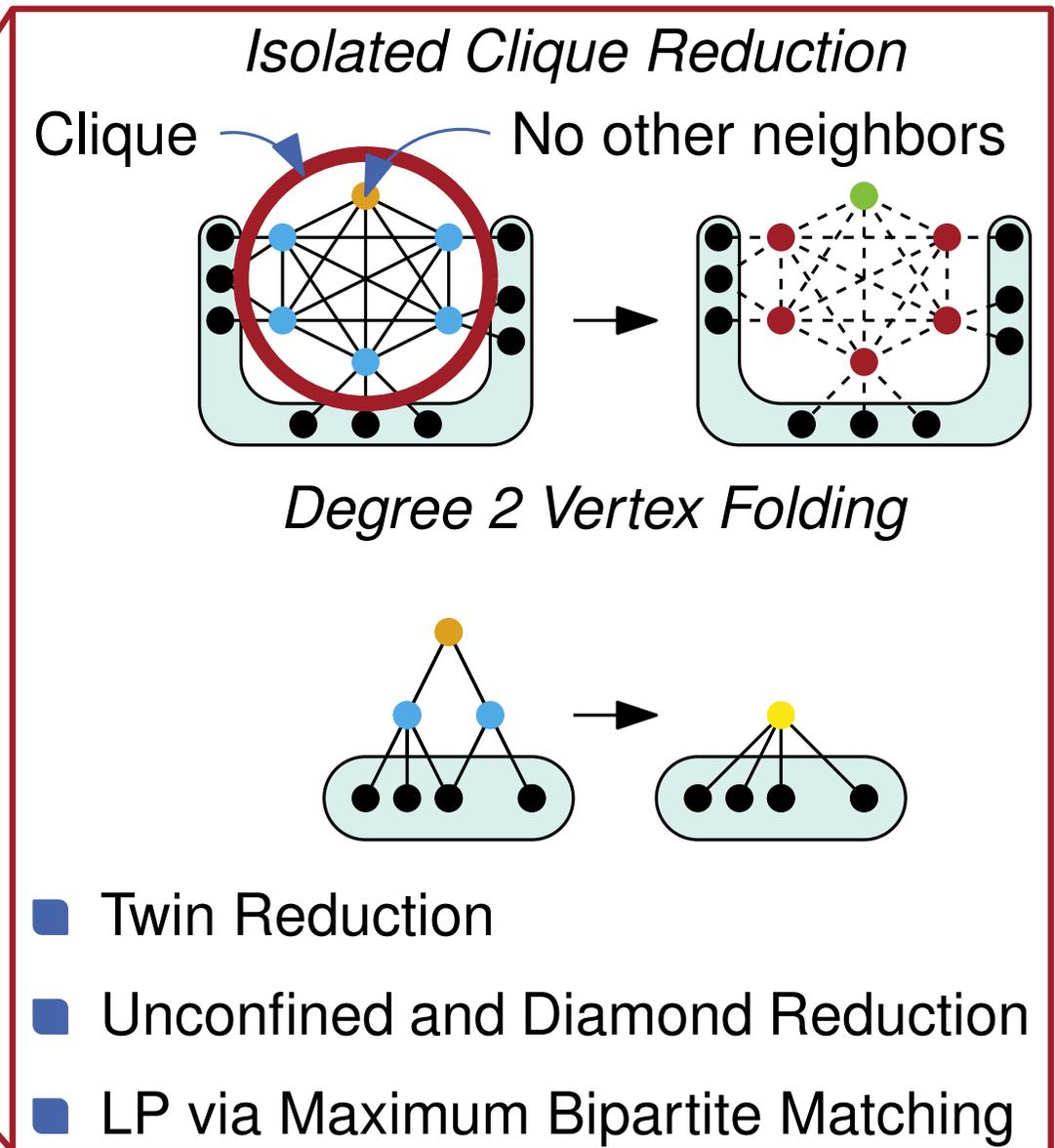
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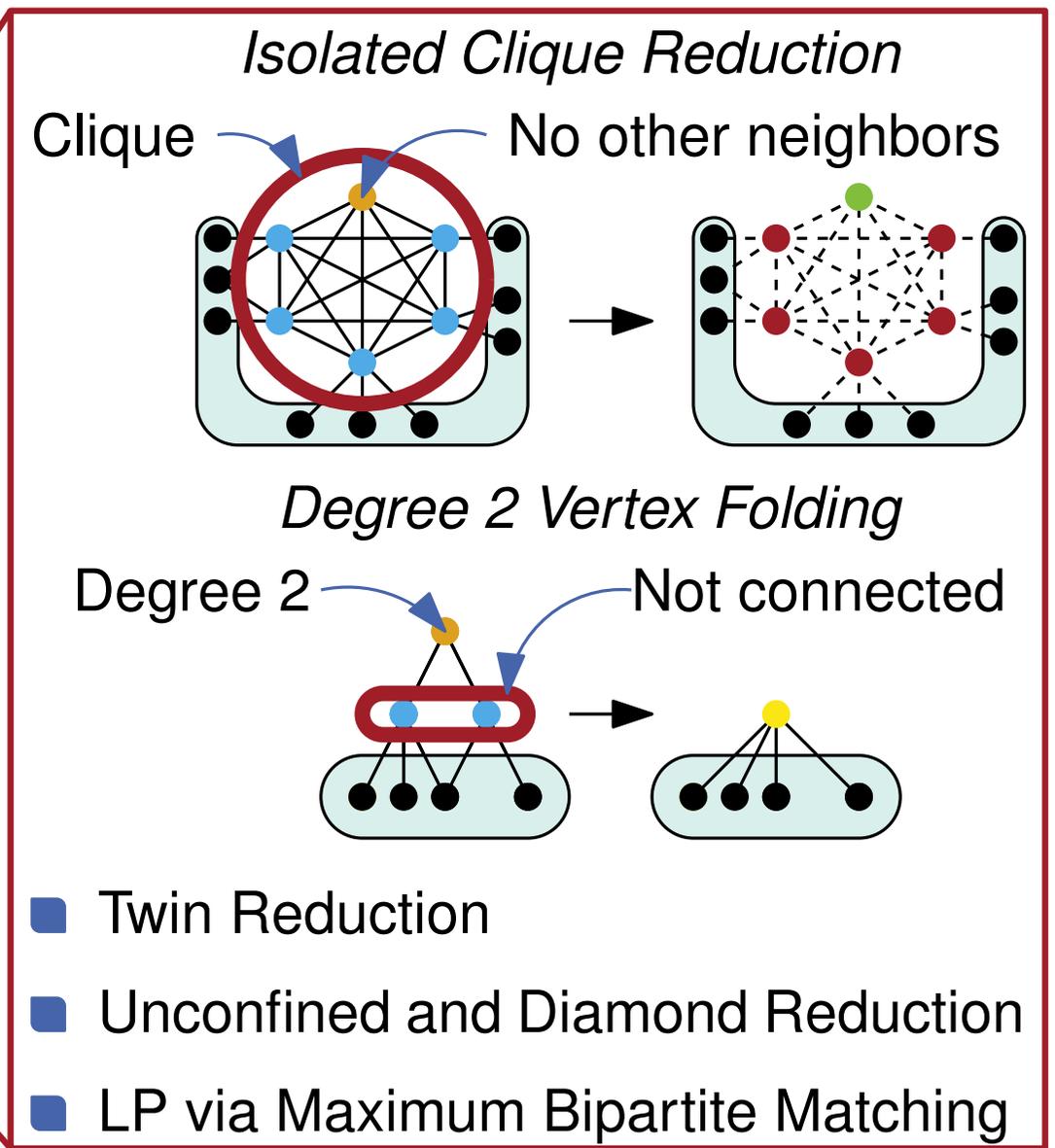
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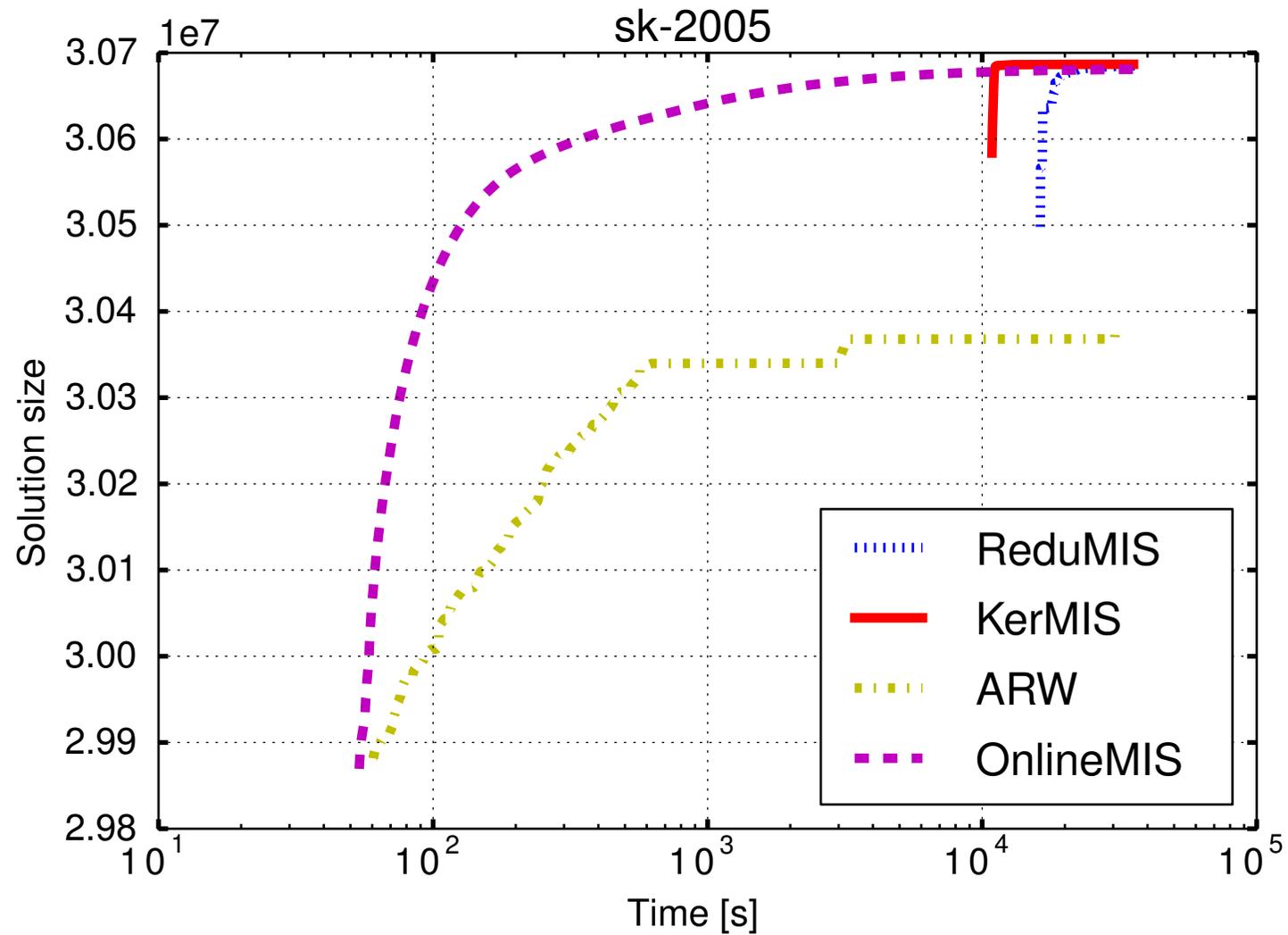
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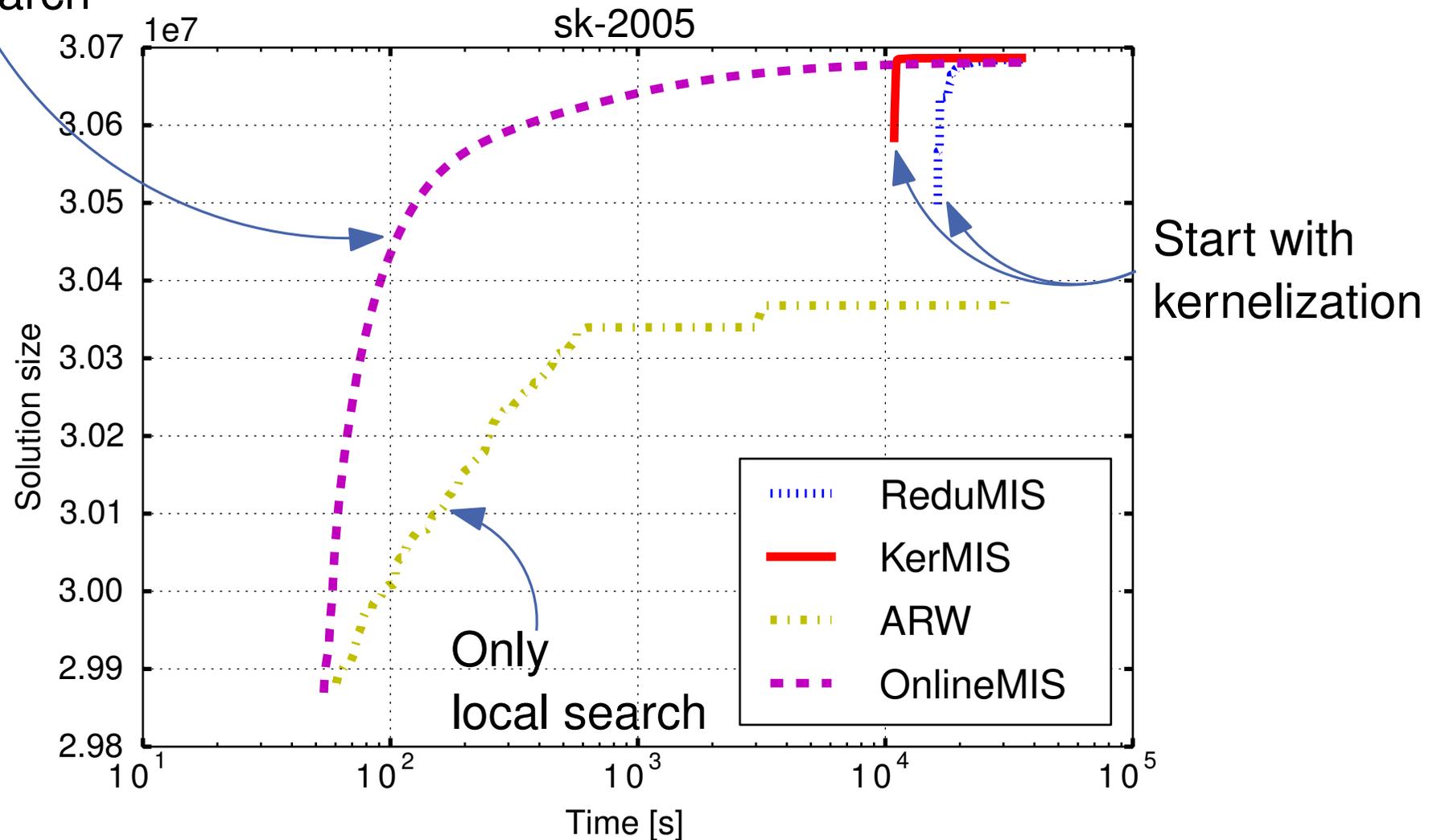


Motivation

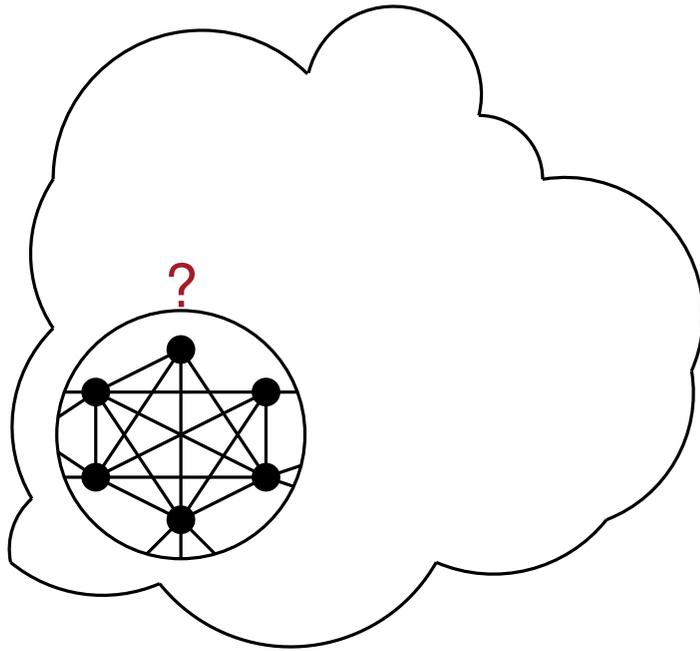


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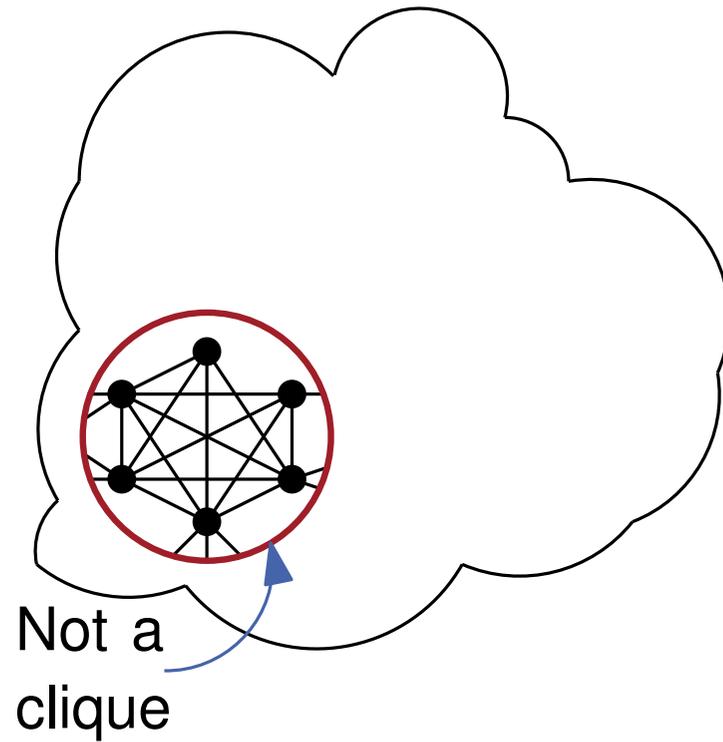
Reductions during
local search



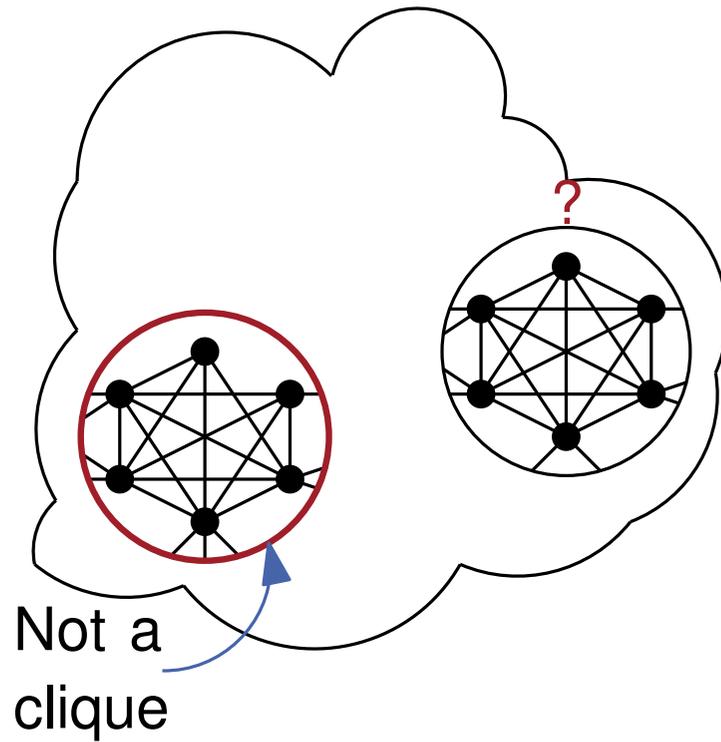
Dependency Checking



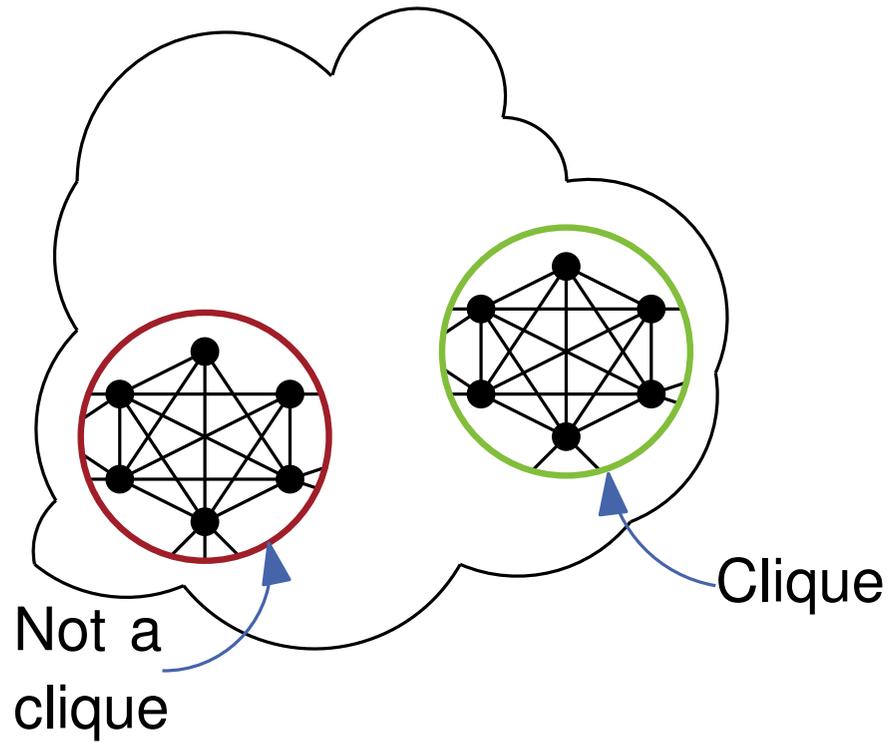
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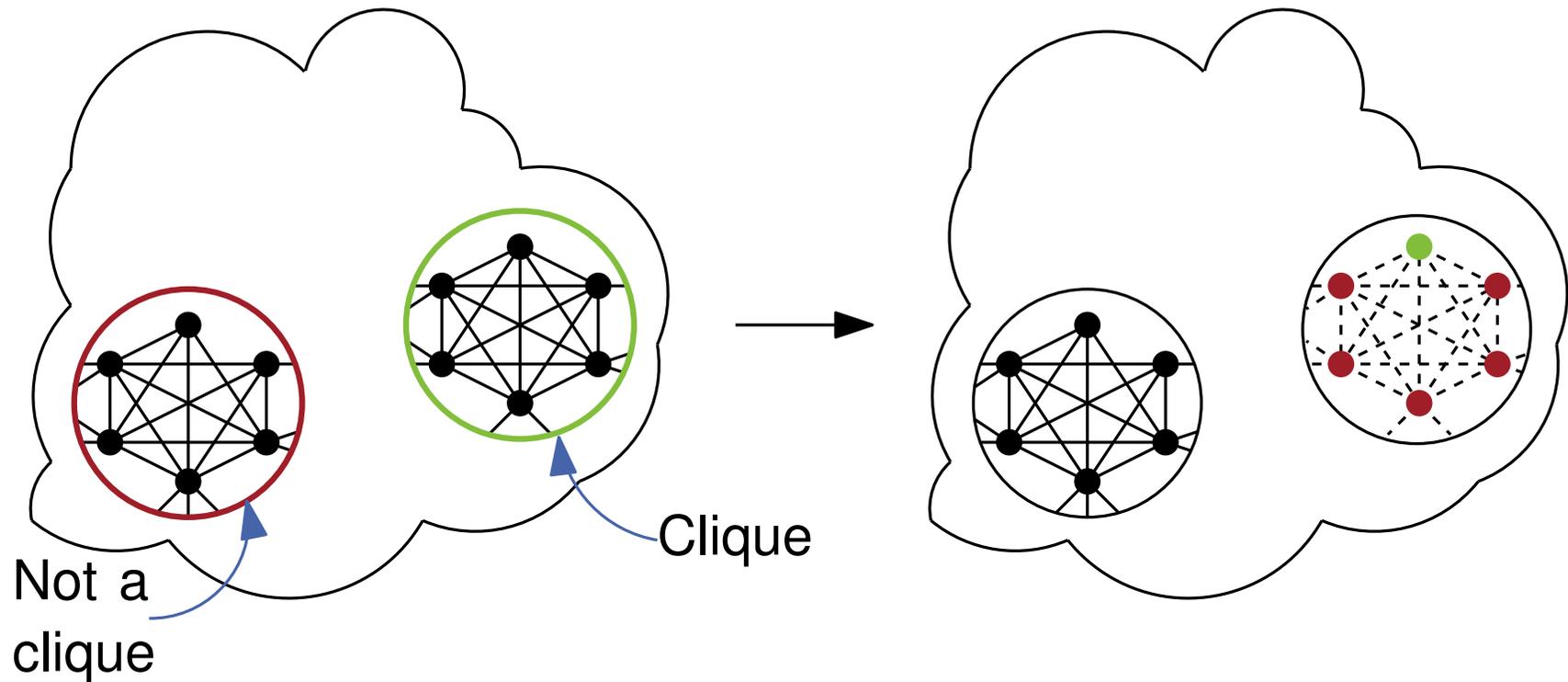
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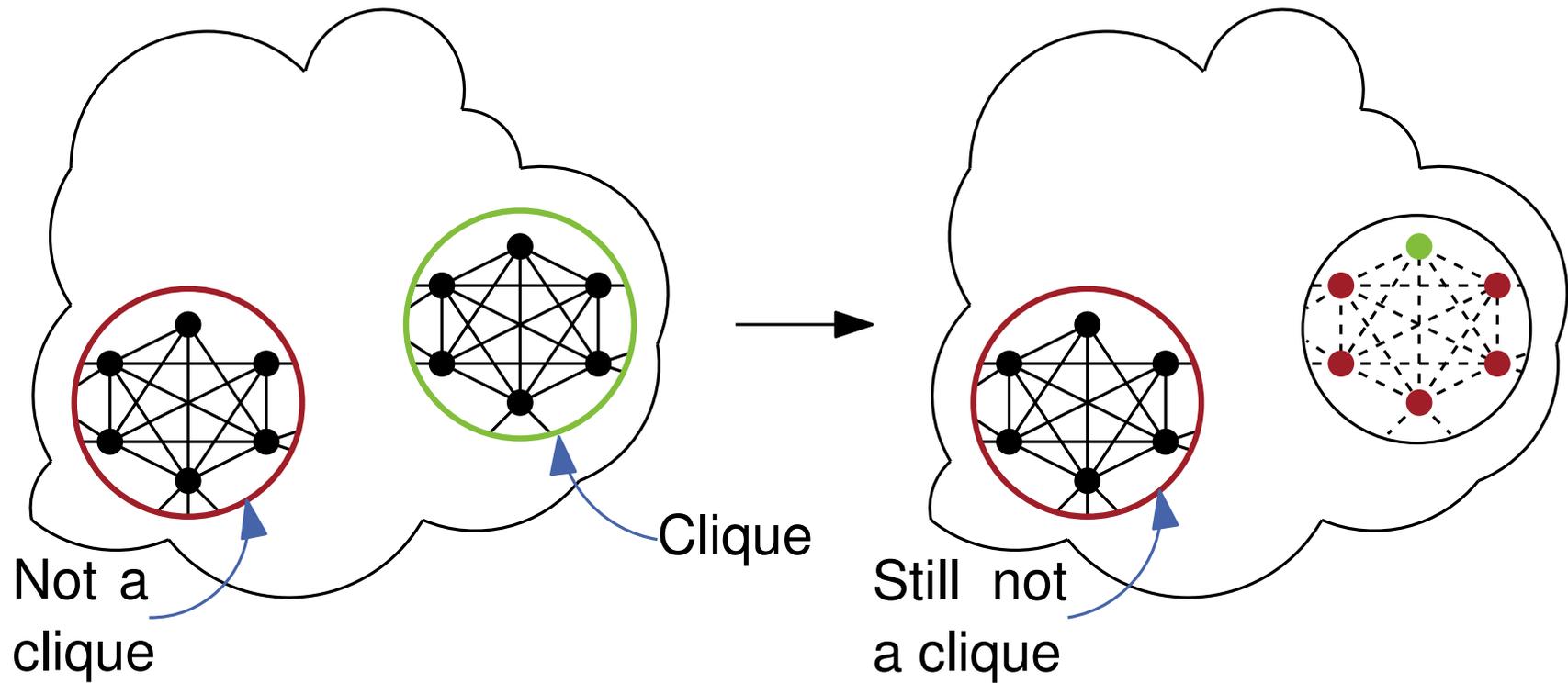
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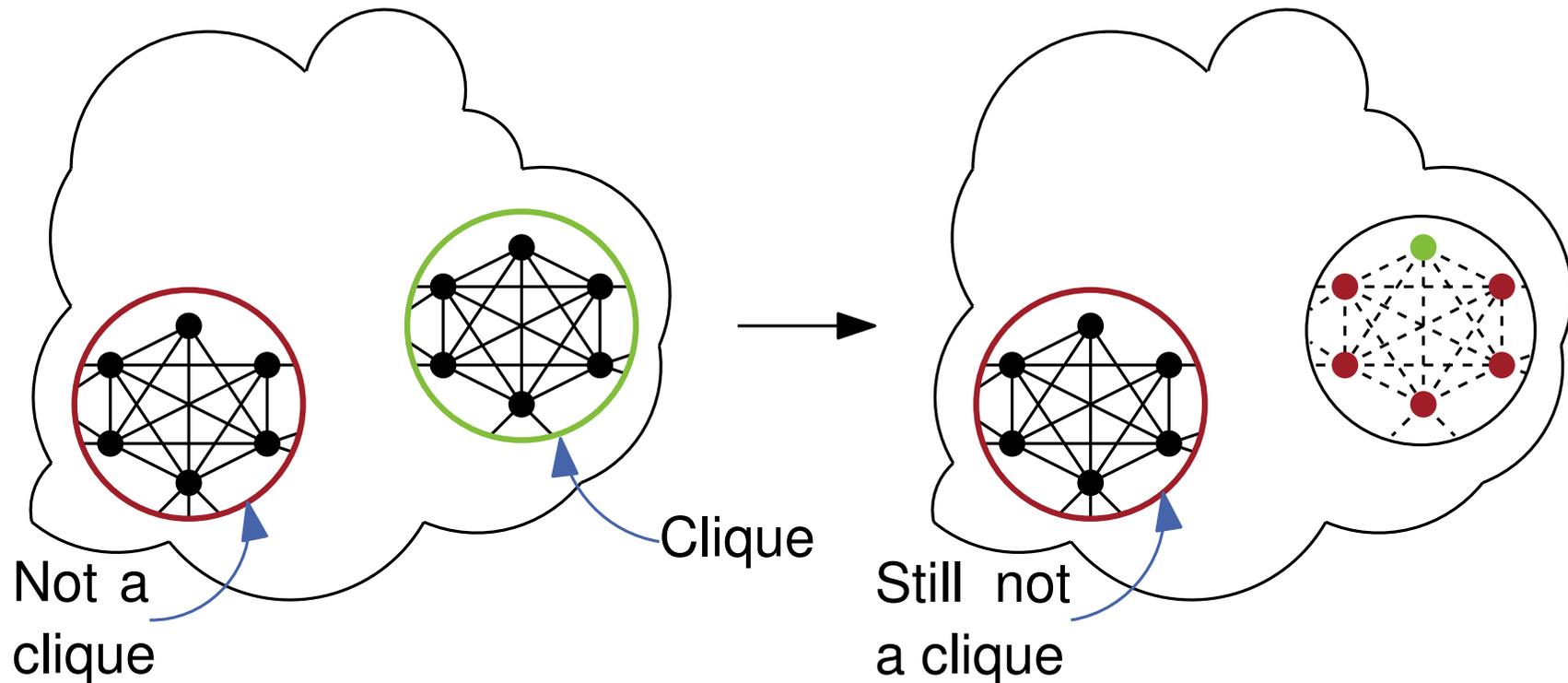
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Dependency Checking



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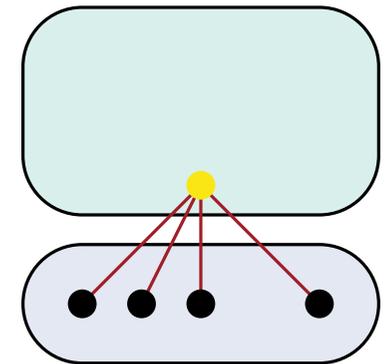
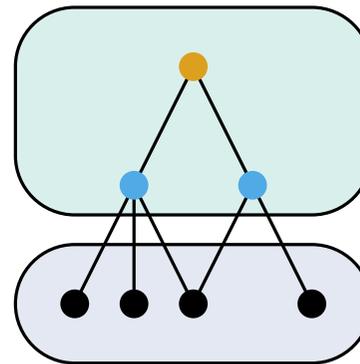
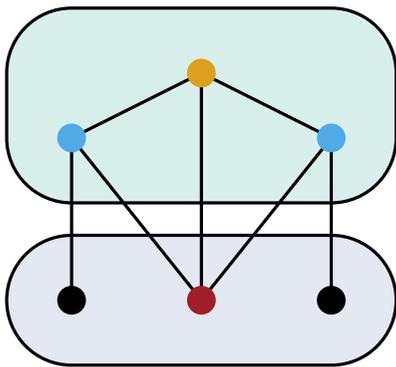


No reduction in G and $N_G(v) = N_{G'}(v) \Rightarrow$ No reduction in G'

- | | | | |
|-----------------------------|---|------------------------|---|
| ■ Isolated Clique Reduction | ✓ | ■ Unconfined Reduction | ✗ |
| ■ Degree 2 Fold Reduction | ✓ | ■ Diamond Reduction | ✗ |
| ■ Twin Reduction | ✓ | ■ LP Reduction | ✗ |

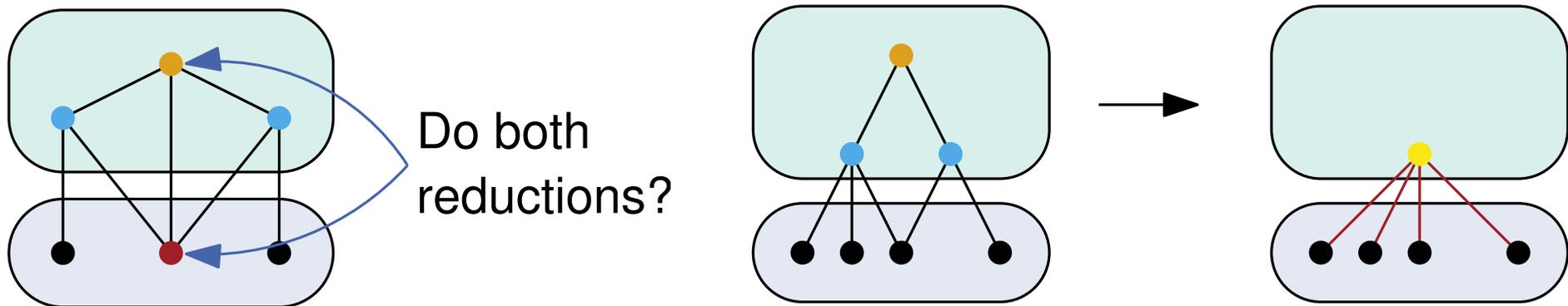
Parallelization by Graph Partitioning

- Idea: Partition graph into blocks and reduce them separately
- Boundaries problematic



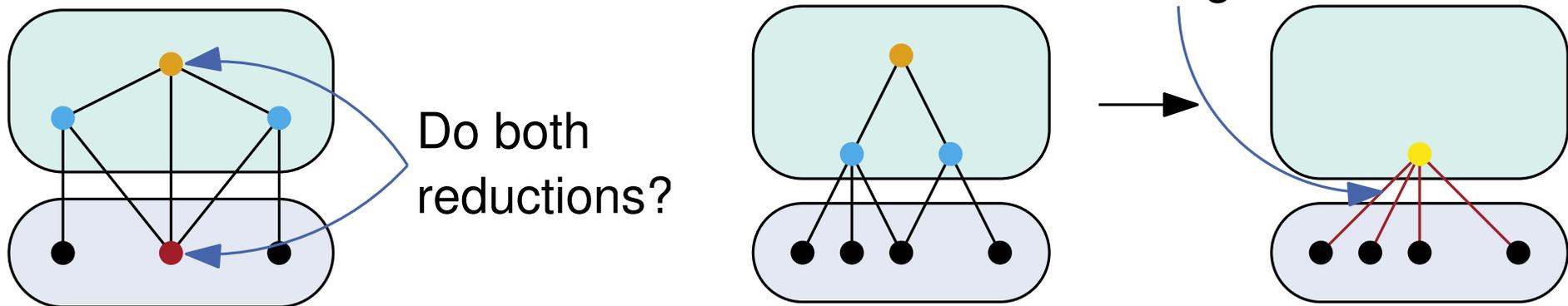
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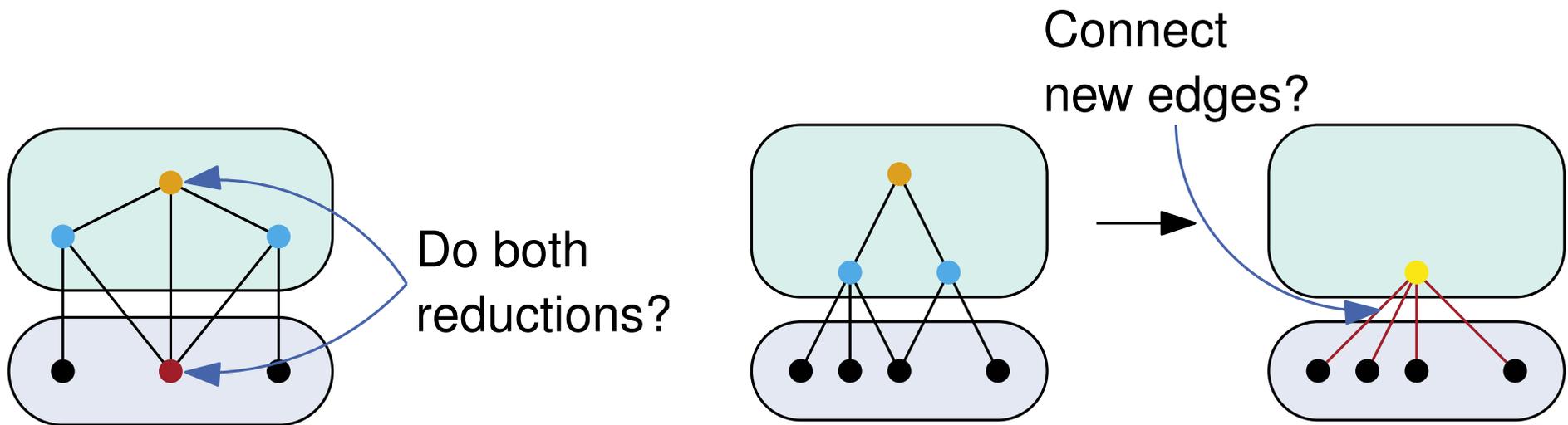
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Parallelization by Graph Partitioning

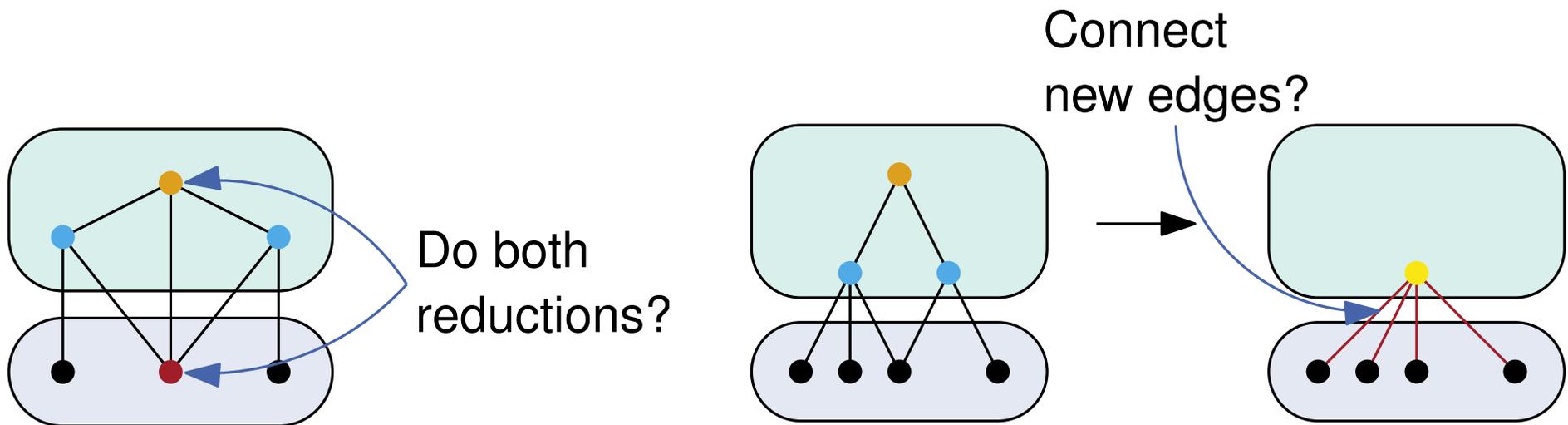
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- ParHIP (part of KaHIP) finds low cuts in parallel [Meyerhenke et al., TPDS'17]

Parallelization by Graph Partitioning

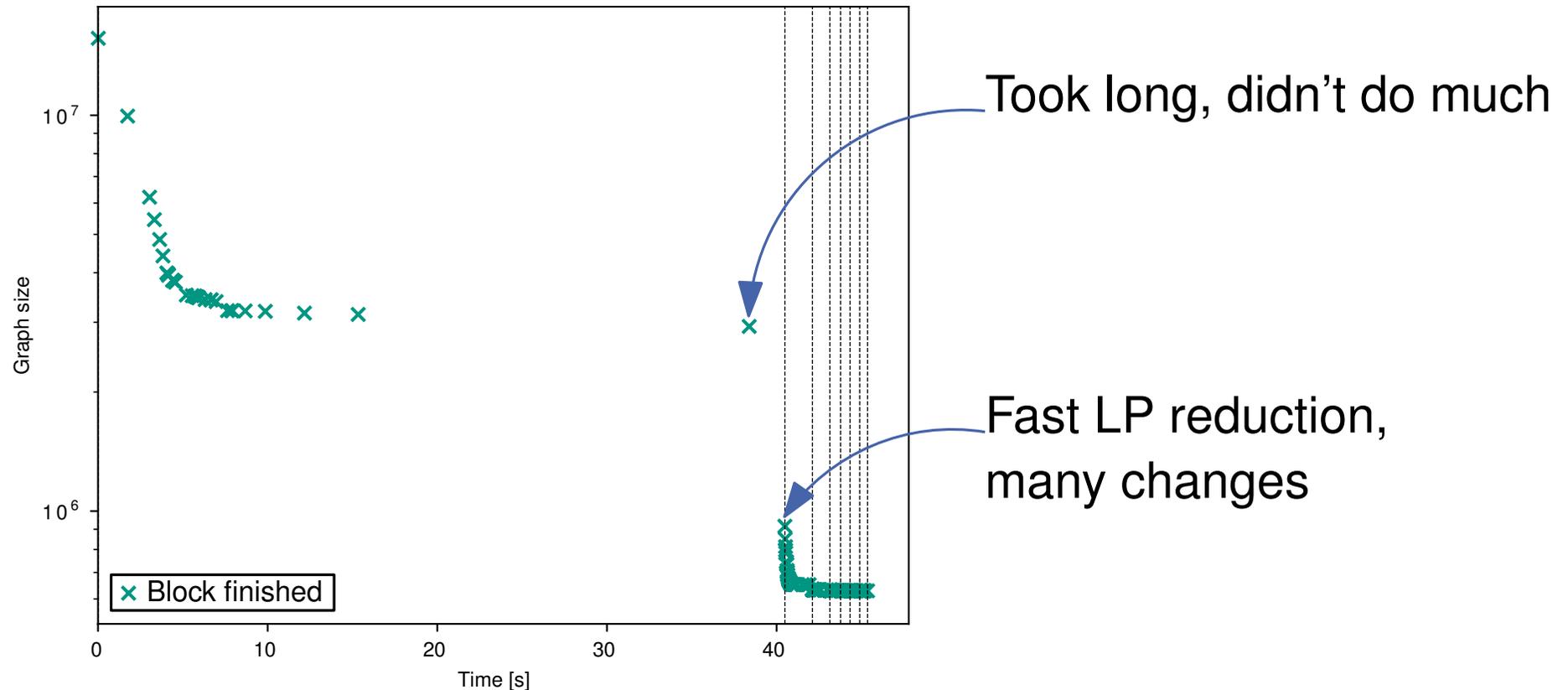
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- ParHIP (part of KaHIP) finds low cuts in parallel [Meyerhenke et al., TPDS'17]
- Parallelize LP reduction with parallel maximum bipartite matching [Azad et al., TPDS'17]

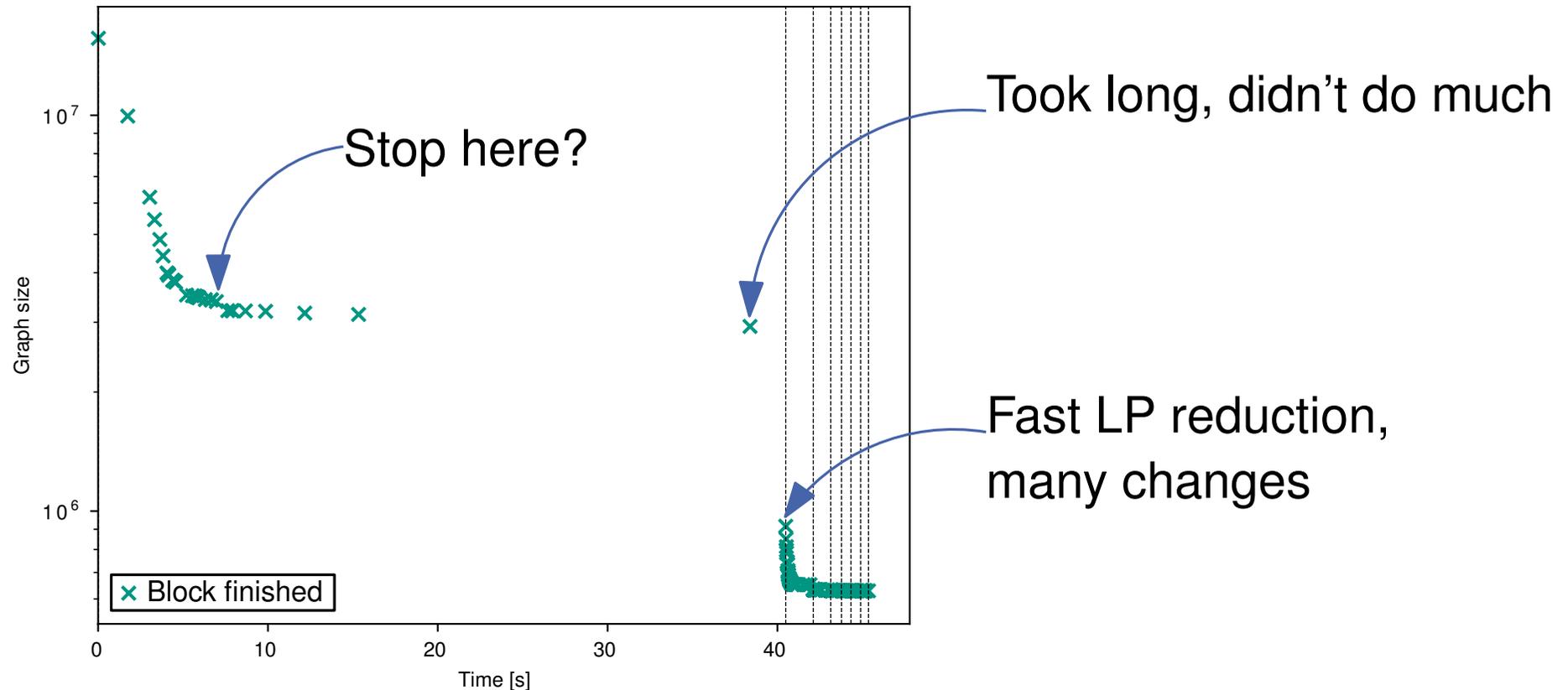
Reduction Tracking

- Some blocks take significantly longer than others
- Few changes after a while



Reduction Tracking

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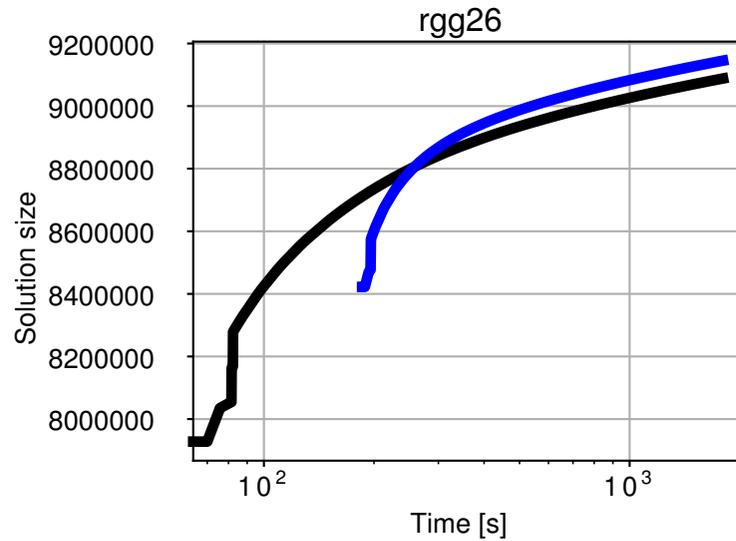
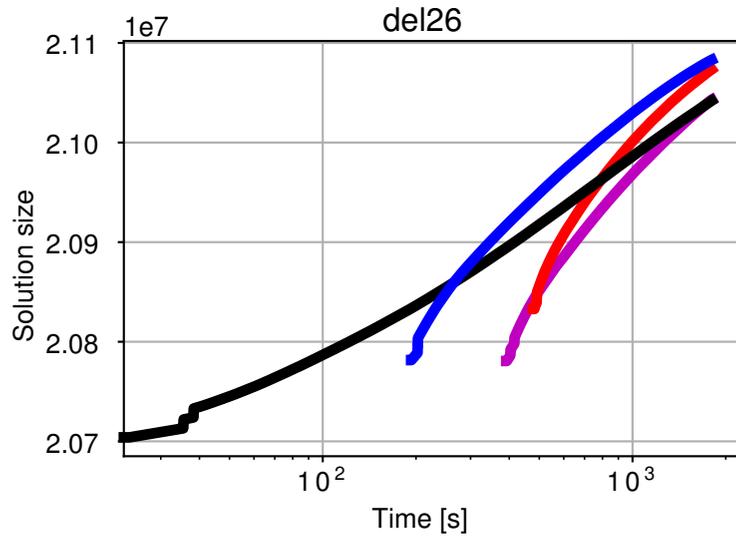
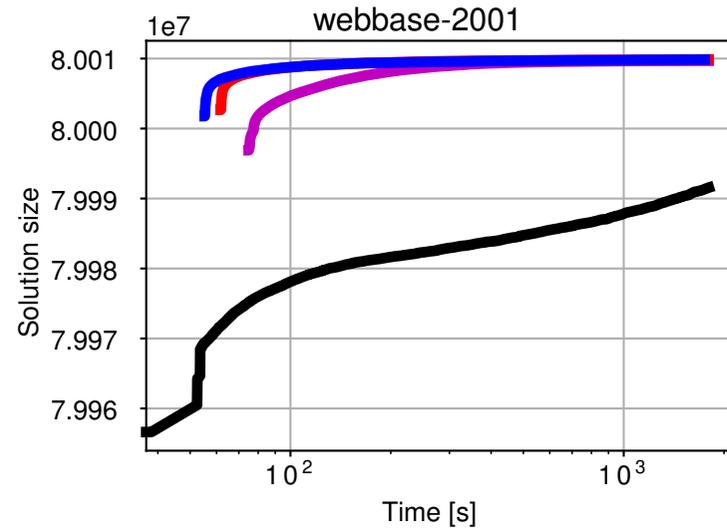
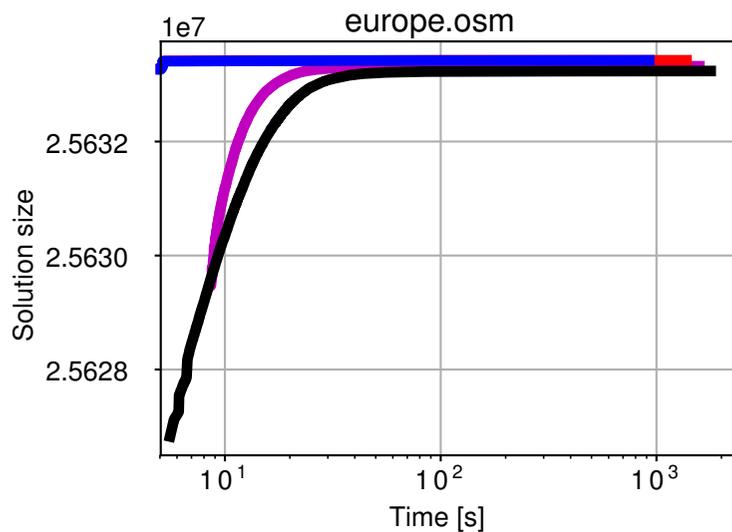


- Start sampling graph size after first block finishes
 - Stop if $\frac{\text{size}_j - \text{size}_{j-1}}{\text{time}_j - \text{time}_{j-1}}$ much smaller than $\frac{\text{size}_j - \text{size}_1}{\text{time}_j - \text{time}_1}$

Experimental Setup

- Implemented in C++, OpenMP
- g++ 5.4 with -O3
- Machine:
 - 2 x Intel Xeon E5-2683 v4 processors (16 cores each)
 - 512 GB Memory
 - Ubuntu 14.04.5 LTS
- Different input graphs with $> 10M$ vertices
 - Real world: Web graphs, road networks
 - Synthetic: RGG, RHG, delaunay triangulations
- Comparison with state of the art algorithms:
 - VCSolver [Akiba and Iwata, TCS'16]: Slow but small
 - LinearTime and NearLinear [Chang et al., MOD'17]: Fast but big
 - We use LinearTime as preprocessing step

Local Search



— NearLinear
 — ParFastKer + NearLinear
 — LinearTime
 — ParFastKer + LinearTime

Conclusion

- Orders of magnitude smaller than fast methods
- Orders of magnitude faster than algorithms with similar sized kernels
- Local search shows: Small kernels matter!
 - We find *larger* independent sets *faster*

Future Work

- What about other MIS algorithms that use kernelization?
- Other problems that use kernelization
 - e.g. undirected feedback vertex set, graph coloring problems