Sanders: Algorithmen II - November 20, ²⁰²³

Algorithmen II

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13 **Onlinealgorithmen** [z.T. von Rob van Stee]

- \Box Information is revealed to the algorithm in parts
- \Box Algorithm needs to process each part before receiving the next
- \Box There is **no information** about the future (in particular, no probabilistic assumptions!)
- How well can an algorithm do compared to an algorithm that knows everything?
- \Box Lack of knowledge vs. lack of processing power

Examples

- Renting Skis etc.
- \Box Paging in ^a virtual memory system
- \Box Routing in communication networks
- \Box Scheduling machines in ^a factory, where orders arrive over time
- Google placing advertisements

Competitive analysis

 \Box Idea: compare online algorithm ALG to offline algorithm OPT

Worst-case performance measure

 \Box Definition:

$$
C_{ALG} = \sup_{\boldsymbol{\sigma}} \frac{\mathsf{ALG}(\boldsymbol{\sigma})}{\mathsf{OPT}(\boldsymbol{\sigma})}
$$

(we look for the input that results in worst re<mark>lative</mark> performance)

 \Box Goal:

find ALG with minimal *^CALG*

A typical online problem: ski rental

 \Box Renting skis costs ⁵⁰ euros, buying them costs ³⁰⁰ euros

- You do not know in advance how often you will go skiing
- \Box Should you rent skis or buy them?

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- You do not know in advance how often you will go skiing
- \Box Should you rent skis or buy them?
- Suggested algorithm: buy skis on the sixth trip
	- Two questions:

 \Box

- $-$ How good is this algorithm?
- $-$ Can you do better?

Upper bound for ski rental

- \Box You plan to buy skis on the sixth trip
- If you make five trips or less, you pay optimal cost (50 euros per trip)
- \Box If you make at least six trips, you pay ⁵⁵⁰ euros
- \Box In this case OPT pays at least ³⁰⁰ euros
- \Box Conclusion: algorithm is $\frac{11}{6}$ -competitive: it never pays more than $\frac{11}{6}$ times the optimal cost

Lower bound for ski rental

 \Box Suppose you buy skis earlier, say on trip *^x* < ⁶. You pay ³⁰⁰+50(*^x*−¹), OPT pays only ⁵⁰*^x*

$$
\frac{250+50x}{50x} = \frac{5}{x} + 1 \ge 2.
$$

 Suppose you buy skis later, on trip *^y* > ⁶. You pay ³⁰⁰+50(*^y*−¹), OPT pays only ³⁰⁰

$$
\frac{250+50y}{300} = \frac{5+y}{6} \ge 2.
$$

 Idea: do not pay the large cost (buy skis) until you would have paid the same amount in small costs (rent)

Paging

 \Box Computers usually have ^a small amount of fast memory (cache)

- This can be used to store data (pages) that are often used
- \Box Problem when the cache is full and ^a new page is requested
- Which page should be thrown out (evicted)?

Definitions

- \Box k = size of cache (number of pages)
- We assume that access to the cache is free, since accessing external memory costs much more
- \Box Thus, ^a cache hit costs ⁰ and ^a miss (fault) costs ¹
- \Box The goal is to minimize the number of page faults

Paging algorithms

Longest Forward Distance is optimal

We show: any optimal offline algorithm can be changed to <mark>act like LFD</mark> without increasing the number of page faults.

Inductive claim: given an algorithm ALG, we can create ALG $_i$ such that

ALG and ALG*ⁱ* act identically on the first *ⁱ*−¹ requests

 \Box If request *ⁱ* causes ^a fault (for both algorithms), ALG*i* evicts page with longest forward distance

$$
\Box \ \text{ALG}_i(\sigma) \leq \text{ALG}(\sigma)
$$

Using the claim

- \Box Start with a given request sequence σ and an optimal offline algorithm ALG
- Use the claim for $i = 1$ on ALG to get ALG_1 , which evicts the LFD page on the first request (if needed)
- \Box Use the claim for $i = 2$ on ALG_1 to get ALG_2

Proof of the claim

not this time

Comparison of algorithms

- \Box OPT is not online, since it looks forward
- Which is the best online algorithm?

 \Box LIFO is not competitive: consider an input sequence

 $p_1, p_2, \ldots, p_{k-1}, p_k, p_{k+1}, p_k, p_{k+1}, \ldots$

 \Box LFU is also not competitive: consider

$$
p_1^m, p_2^m, \ldots, p_{k-1}^m, (p_k, p_{k+1})^{m-1}
$$

A general lower bound

- \Box To illustrate the problem, we show a lower bound for any online paging algorithm ALG
- There are $k+1$ pages
- \Box At all times, ALG has *^k* pages in its cache
- \Box There is always one page missing: request this page at each step
- \Box OPT only faults once every *^k* steps
	- \Rightarrow lower bound of k on the competitive ratio

Resource augmentation

 \Box We will compare an online algorithm ALG to an optimal offline algorithm which has ^a smaller cache

We hope to get more realistic results in this way

 \Box Size of offline cache $= h < k$

 \Box This problem is known as (*^h*,*^k*)-paging

Conservative algorithms

- \Box An algorithm is conservative if it has at most *^k* page faults on any request sequence that contains at most *k* distinct pages
- The request sequence may be arbitrarily long
- \Box LRU and FIFO are conservative
- \Box LFU and LIFO are not conservative (recall that they are not competitive)

Competitive ratio

Theorem: Any conservative algorithm is *^k ^k*−*h*+¹ -competitive

Proof: divide request sequence ^σ into **phases**.

 \Box Phase 0 is the empty sequence

 \Box Phase *ⁱ* > ⁰ is the maximal sequence following phase *ⁱ*−¹ that contains at most *k* distinct pages

Phase partitioning does not depend on algorithm. ^A conservative algorithm has at most *k* faults per phase.

Counting the faults of OPT

Consider some phase $i > 0$, denote its first request by f

Thus OPT has at least $k - (h - 1) = k - h + 1$ faults on the grey requests

Conclusion

 \Box In each phase, ^a conservative algorithm has *^k* faults

 To each phase except the last one, we can assign (charge) $k - h + 1$ faults of OPT

 \Box Thus

 \Box

$$
\text{ALG}(\sigma) \leq \frac{k}{k - h + 1} \cdot \text{OPT}(\sigma) + r
$$

where $r\leq k$ is the number of page faults of ALG in the last phase

This proves the theorem

Notes

- \Box For $h = k/2$, we find that conservative algorithms are 2-competitive
- The previous lower bound construction does not work for $h < k$
- \Box In practice, the "competitive ratio" of LRU is a small constant
- \Box Resource augmentation can give better (more realistic) results than pure competitive analysis

New results (Panagiotou & Souza, STOC 2006)

- \Box Restrict the adversary to get more "natural" input sequences
- Locality of reference: most consecutive requests to pages have short distance
- \Box Typical memory access patterns: consecutive requests have either short or long distance compared to the cache size

Randomized algorithms

- \Box Another way to avoid the lower bound of *^k* for paging is to use ^a randomized algorithm
- Such an algorithm is allowed to use random bits in its decision making
- \Box Crucial is what the adversary knows about these random bits

Three types of adversaries

 \Box Oblivious: knows only the probability distribution that ALG uses, determines input in advance

 Adaptive online: knows random choices made so far, bases input on these choices

 \Box Adaptive offline: knows random choices in advance (!)

Randomization <mark>does not help</mark> against adaptive offline adversary

We focus on the <mark>oblivious</mark> adversary

Marking Algorithm

 \Box marks pages which are requested

- never evicts ^a marked page
- \Box When all pages are marked and there is a fault, unmark everything (but mark the page which caused the fault)(new phase)

Marking Algorithms

Only difference is eviction strategy

LRU

\Box FWF

 \Box RMARK: Evict an unmarked page choosen uniformly at random

Competitive ratio of RMARK

 $\bf Theorem\colon RMARK$ is $2H_k$ -competitive

where

$$
H_k = 1 + \frac{1}{2} + \frac{1}{3} + \dots + \frac{1}{k} \le \ln k + 1
$$

is the *^k*-the harmonic number

Analysis of RMARK

Consider ^a phase with *^m* new pages

(that are not cached in the beginning of the phase)

Miss probability when $j+1$ st <mark>old</mark> page becomes marked

1 -
$$
\frac{\text{# old unmarked cached pages}}{\text{# old unmarked pages}} \le 1 - \frac{k - m - j}{k - j} = \frac{m}{k - j}
$$

Overall expected number of faults (including <mark>new</mark> pages):

$$
m + \sum_{j=0}^{k-m-1} \frac{m}{k-j} = m + m \sum_{i=m+1}^{k} \frac{1}{i} = m(1 + H_k - H_m) \leq mH_k
$$

Lower bound for OPT

There are *^mⁱ* new pages in phase *ⁱ*

 \Box Thus, in phases $i-1$ and i together, $k+m_i$ pages are requested

OPT makes at least *^mⁱ* faults in phases *ⁱ* and *ⁱ*−¹ for any *ⁱ*

 \Box Total number of OPT faults is at least $\frac{1}{2} \sum_i m_i$

Upper bound for RMARK

- \Box Expected number of faults in phase *i* is at most $m_i H_k$ for RMARK
- Total expected number of faults is at most $H_k \sum_i m_i$
- \Box OPT has at least $\frac{1}{2} \sum_i m_i$ faults
- Conclusion: RMARK is ²*Hk*-competitive

Randomized lower bound

 $\bf Theorem\colon$ No randomized can be better than H_k -competetive against an oblivious adversary.

Proof: not here

Discussion

^H^k [≪] *^k*

 The upper bound for RMARK holds against an oblivious adversary (the input sequence is fixed in advance)

 \Box No algorithm can be better than H_k -competitive

 \Box Thus, RMARK is optimal apart from ^a factor of ²

 \Box There is ^a (more complicated) algorithm that is *^H^k* competetive

Why competitive analysis?

There are many models for "decision making in the absence of complete information"

- \Box Competitive analysis leads to algorithms that would not otherwise be considered
- \Box Probability distributions are rarely known precisely
- Assumptions about distributions must often be unrealistically crude to allow for mathematical tractability
- \Box Competitive analysis gives ^a guarantee on the performance of an algorithm, which is essential in e.g. financial planning

Disadvantages of competitive analysis

 \Box Results can be too pessimistic (adversary is too powerful)

- $-$ Resource augmentation
- –— Randomization
- $-$ Restrictions on the input

 Unable to distinguish between some algorithms that perform differently in practice

- $-$ Paging: LRU and FIFO
- – $-$ more refined models