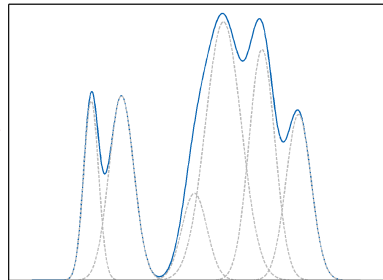
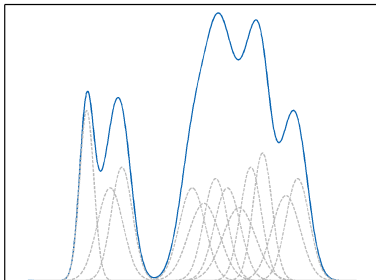


Clustering-based Gaussian Mixture Reduction

Dennis Schieferdecker - 09.06.09

GRK 1194: Self-organizing Sensor-Actuator-Networks

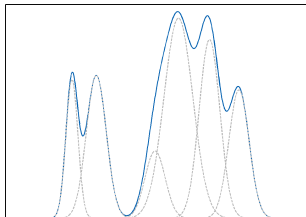


Gaussian Mixture Density

- weighted sum of Gaussians

$$f(x; \underline{\eta}) = \sum_{i=1}^N \omega_i \cdot \mathcal{N}(x; \mu_i, \sigma_i^2)$$

- universal function approximator
- possible applications
 - target tracking,
 - density estimation,
 - ...



Problems in Application

- recursive multiplication of Gaussian mixtures
- number of components grows rapidly (exponential growth)

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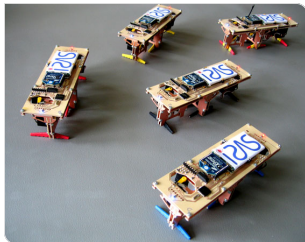
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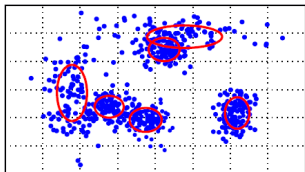
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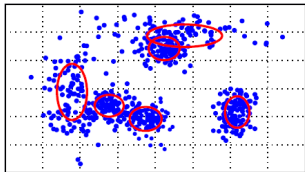
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- recursive multiplication of Gaussian mixtures
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Problem Description

Gaussian Mixture Reduction

Goal

- given a mixture $\underline{\tilde{\eta}}$ with N components (true/original mixture),
- find a mixture $\underline{\eta}$ with $K < N$ components (reduced mixture),
- so that a deviation measure $d(\underline{\tilde{\eta}}, \underline{\eta})$ is minimized.

Deviation Measures

- Integrated Squared Distance (ISD):
$$d(f_1(x), f_2(x)) = \int_{\mathbb{R}} (f_1(x) - f_2(x))^2 dx$$
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Reduction Methods

Overview

top-down approaches

- greedy methods
- iteratively replace two Gaussians with one
- chosen according to a deviation measure (local, global, hybrid)

bottom-up approach

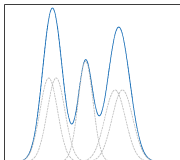
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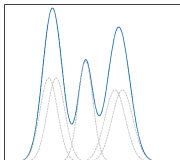


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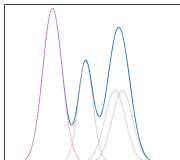
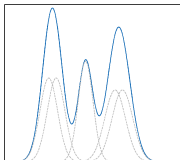


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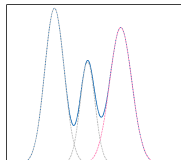
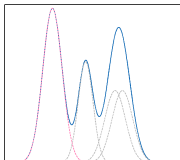
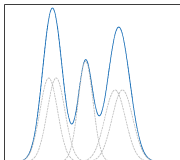


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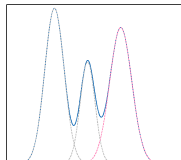
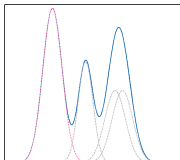
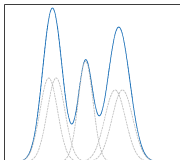


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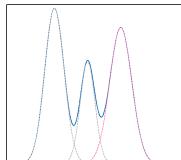
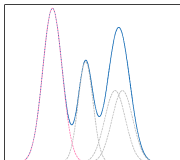
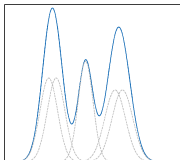


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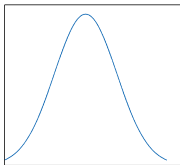
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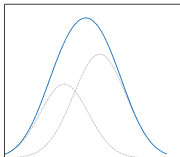


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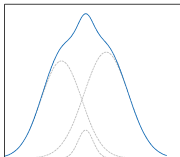


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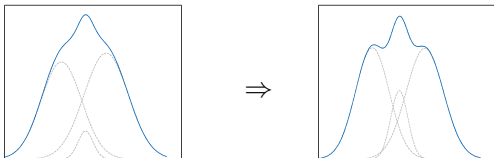


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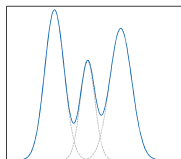
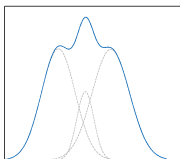
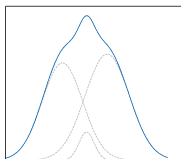


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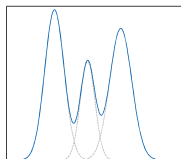
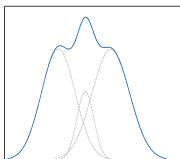
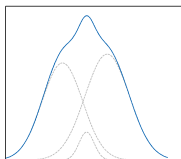


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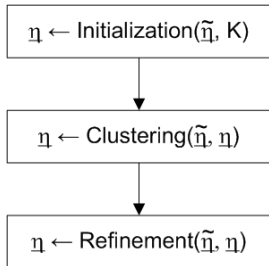
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- **PGMR - state-of-the-art**



Gaussian Mixture Reduction via Clustering (GMRC)

- modular three-step algorithm
- input:
 - $\tilde{\eta}$ (parameter vector of the original mixture)
 - \bar{K} (number of reduced components)
- output:
 - η (parameter vector of the reduced mixture)

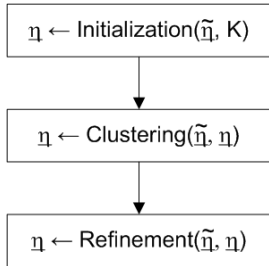


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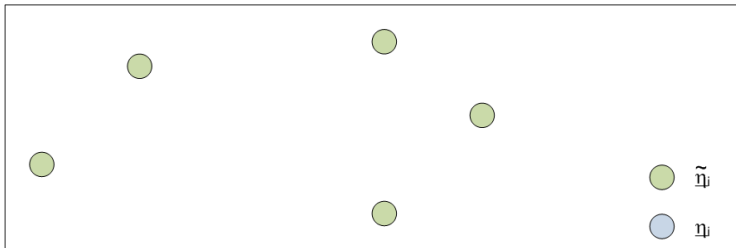
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Initialization Step

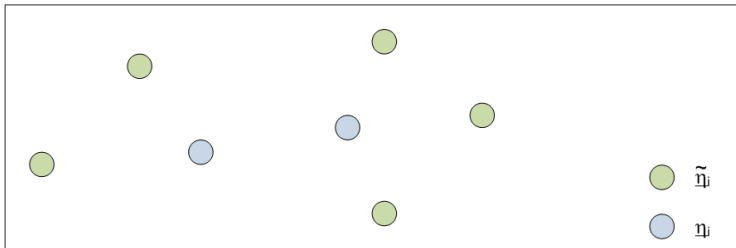
- compute a preliminary solution $\underline{\eta}$ (i.e. using West, Runnalls, ...) → initial cluster centers
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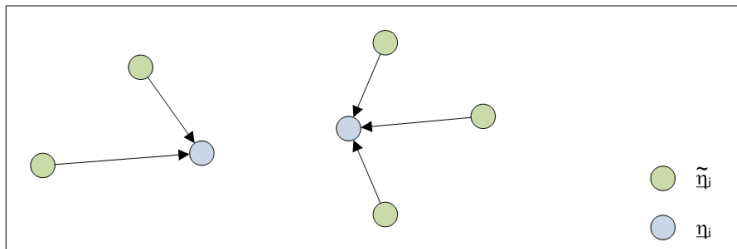
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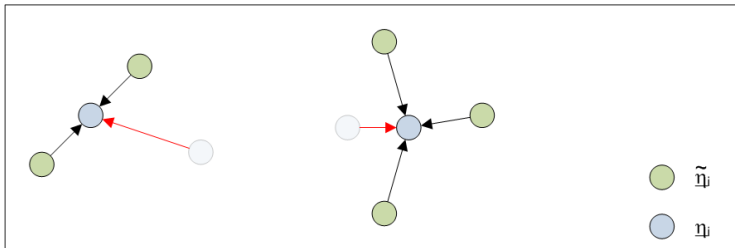
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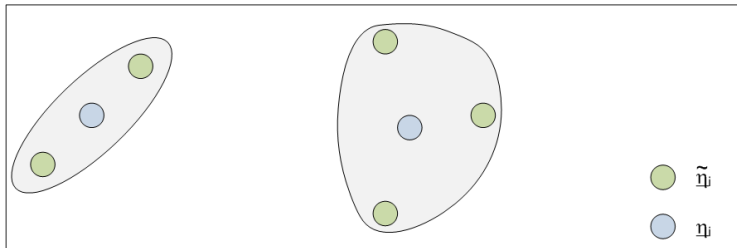
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- greedy approach
- based on Lloyd's algorithm (**k-means algorithm**):
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determine the 'nearest' center

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- optimize parameter vector $\underline{\eta}$ w.r.t. ISD

$$\min_{\underline{\eta}} \int_{\mathbb{R}} \left(\tilde{f}(x; \tilde{\eta}) - f(x; \underline{\eta}) \right)^2 dx$$

- non-linear optimization problem → **Newton approach**
- finds local optimum

Weight Optimization

- system of linear equations
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Refinement Step

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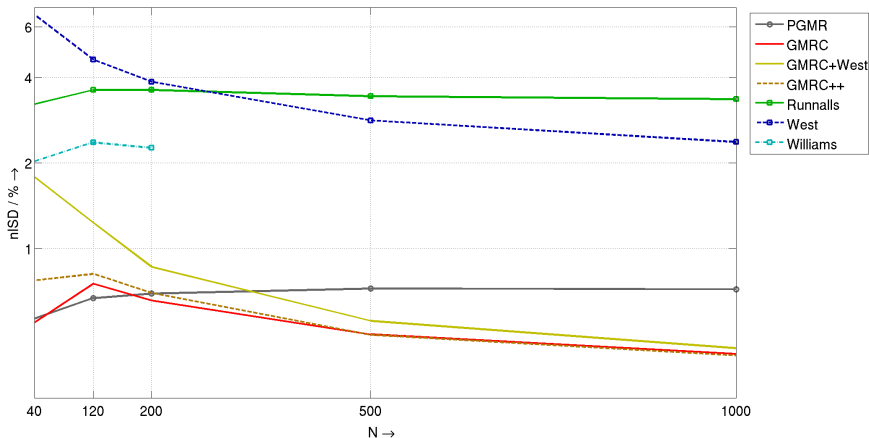
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Simulation Setup

- Office PC (Intel Core2 Duo E8400)
 - OpenSUSE 11.0
 - Matlab 7.7.0 (R2008b)
-
- reduction of mixtures with $N \in \{40, 120, 200, 500, 1000\}$ components down to $K = 10$
 - each evaluated with 1 000 simulation runs

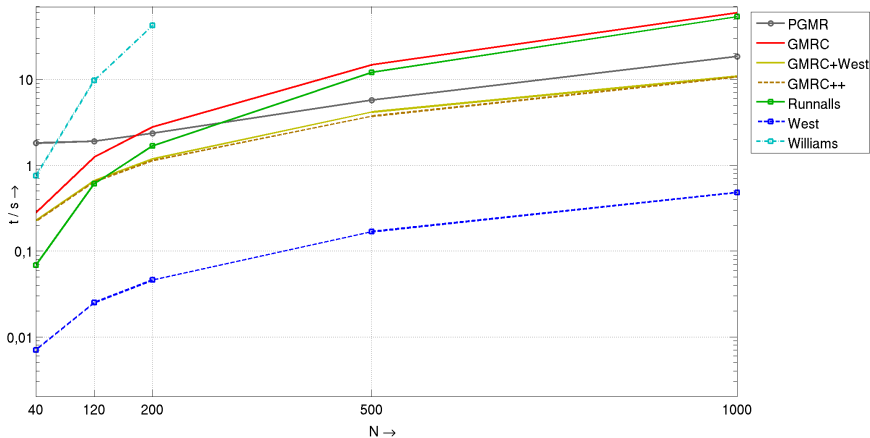
Results

Approximation Quality



Results

Running Time



Results

Impact of Individual Steps

	algorithm	running time	norm. ISD
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	w. random init.	$1.135 \pm 0.045s$	1.272 ± 1.561
	w/o clustering	$1.742 \pm 0.043s$	0.774 ± 0.872
	w/o refinement	$2.737 \pm 0.036s$	1.697 ± 0.432
Runnalls		$1.678 \pm 0.024s$	3.606 ± 0.752

(initialization with **Runnalls' algorithm**; $N = 200, K = 10$)

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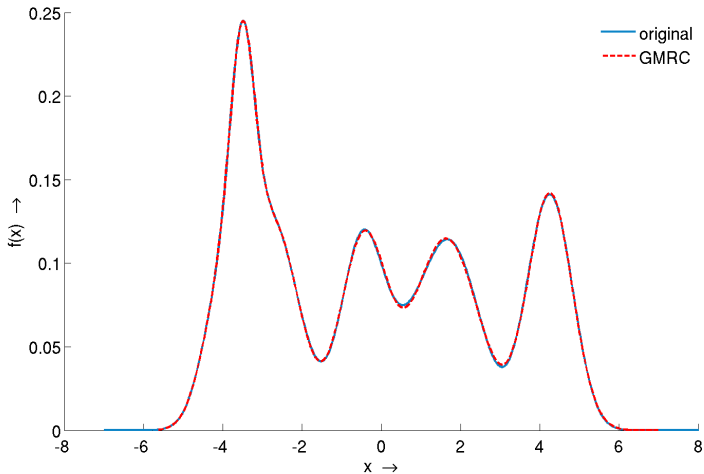
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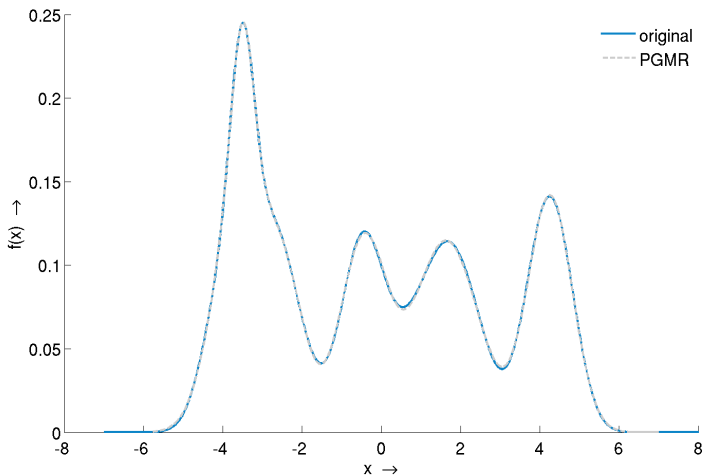
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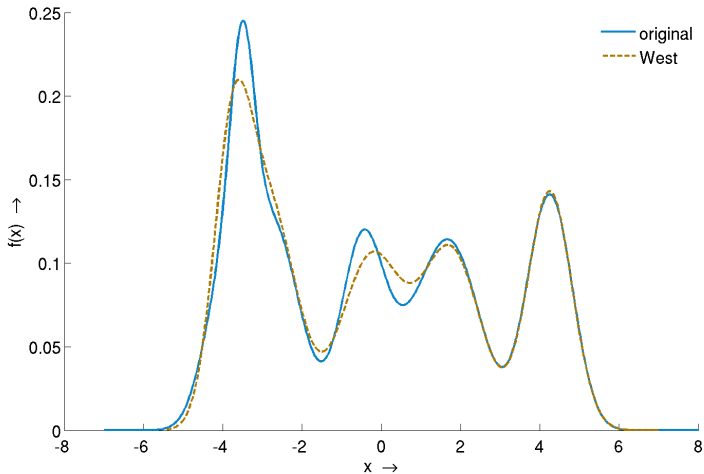
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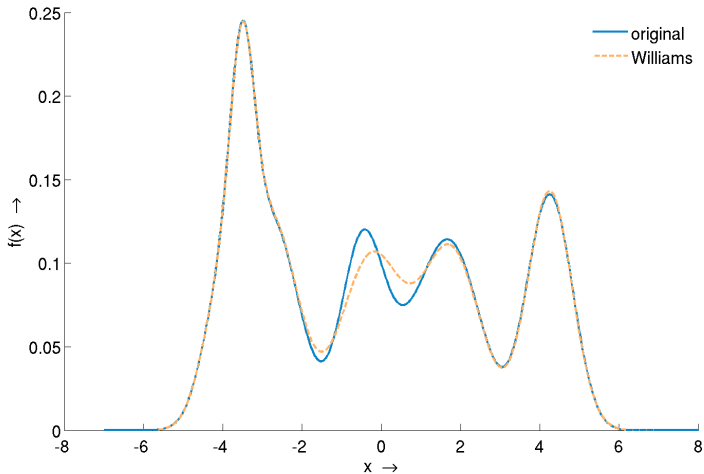
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Thank you for your attention!



time for questions